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A Two-dimensional Systematic Survey of the Iceland Scallop, Chlamys islandica in the Strait of Belle Isle

## by

K.S. Naidu and S.J. Smith ${ }^{1}$ Department of Fisheries \& Oceans

Fisheries Research Branch
P.O. Box 5667

St. John's, Newfoundland
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ABSTRACT
The use of a systematic lattice sampling scheme to obtain estimates of exploitable scallop (Chlamys islandica) biomass in the Strait of Belle Isle is investigated here. ProbTems in variance estimation, which heretofore limited the use of this method for the enumeration of animal population are also discussed.

RESUME
Nous examinons ici un schéma d'échantillonnage systématique en treillis pour estimer la biomasse exploitable des pétoncles (Chlamys islandica) du dētroit de Belle-Isle. Nous considērons également les problèmes que pose l'estimation de la variance, problèmes qui, jusqu'à maintenant, avaient limité l'utilisation de cette méthode dans le dénombrement d'une population animale.
${ }^{1}$ Department of Fisheries \& Oceans, Marine Fish Division, Bedford Institute of Oceanography, P.O. Box 1006, Dartmouth, N.S. B2Y 4A2

## INTRODUCTION

A fishery for the Iceland scallop developed in the northeastern Gulf of St. Lawrence in 1969. Annual landings during the first six years of the fishery ranged from 151 mt in 1971 to 2342 mt in 1972 with a mean at 847 mt . There was no active fishery for the mollusc between 1975 and 1978 (inclusive). The fishery resumed in 1979 when 430 mt were taken. Landings increased to 1022 and 1380 mt in 1980 and 1981 (provisional) respectively with landed value for the two parts combined exceeding 2 M dollars. The recent resurgence of fishing in this area has renewed our interest in this stock, particularly from the point of carrying out suitable assessments and developing appropriate management regimes for the fishery.

In 1980 and 1981 sample surveys based on a systematic lattice design were carried out over the main fishery area with two objectives in mind, 1) to explore and determine the spatial structure of the scallop population and 2) to assess the suitability of using this type of sampling design for stock management purposes.

The main advantage being sought here by applying a systematic scheme, aside from ease of design and the fact that little 'a priori' information is required (in contrast to stratified designs), is that under certain conditions this design provides more precise estimates of the population mean than random or random-stratified schemes (Cochran 1977). The major drawback in using this method is that there is no general estimator of this precision. Methods of dealing with this problem for the case at hand are discussed.

## METHODS

## I. Survey Design

The procedures involved in setting up a systematic lattice design are described in Smith and Naidu (1981). Briefly, the area to be sampled is divided up into a $N_{1} \times N_{2}$ rectangular lattice with $N_{1}=K_{1}, n_{1}$, rows and $N_{2}=K_{2} n_{2}$ columns, ( $K_{1}, K_{2}, n_{1}, n_{2}$ all integers) such that there are $N=N_{1} N_{2}$ possible sample units of equal size available. The sample positions are obtained by randomly choosing integers $i^{\prime}$ and $j^{\prime}$ from the ranges $1, \ldots, K_{1}$ and $1, \ldots, K_{2}$ respectively. The sample will then consist
of those units identified by the $n_{1} \times n_{2}$ combinations of the row indices $i^{\prime}$, $i^{\prime}+K_{1}, i^{\prime}+2 K_{1}, \ldots, i^{\prime}+\left(n_{1}-1\right) K_{1}$ and column indices $j^{\prime}, j^{\prime}+K_{2}$, $j^{\prime}+2 K_{2}, \ldots, j^{\prime}+\left(n_{2}-1\right) K_{2}$. The structure of the sample will be aligned in both directions, aligned in one direction only or unaligned, depending upon the choice of $\mathrm{i}^{\prime}$ and $\mathrm{j}^{\prime \prime}$. The advantages and disadvantages of using any one of these three alianments are discussed in Bellhouse (1977).

The survey that was carried out deviated from this ideal structure in that the sample area was not rectangular, but the general procedure still applies. The fishing (sample) area was delineated based on information gathered from all the fishermen actively prosecuting the scallop fishery.

Initially the sample units were defined to be the area covered by a $\frac{1}{2}$ mile tow with the dredging gear and bence, under the restriction of the time available the sample grid was set up in the following manner. Eleven latitudinal transects, each spaced one nautica $\overline{1}$ mile apart $\left(K_{1}=639\right)$, were run in the target area (Figure 1). Fishing stations were assigned at $\frac{1}{2}$ mile intervals along these lines. Fishing stations in water less than $30 \mathrm{fms}(55 \mathrm{~m})$ were deleted from the lattice since no conmercial fishing occurred at those depths. Preliminary studies indicated that at a standard tow speed of 3.0 knots the dredging gear tended to "bulldoze" when dragging over a distance of a $\frac{1}{2}$ mile and therefore the sample units were reduced to the area covered in a $0.25 \mathrm{mile}(0.46 \mathrm{~km})$ tow $\left(K_{2}=4\right)$. The total number of stations available in the survey area is 290,745 of which 455 were contained on the eleven transects chosen. Using the value of $K_{2}=4,103$ stations were occupied in 1980 (Figure 1 , closed circles). In 1981 operational constraints imposed principally by inclement weather reduced the coverage to 59 stations (Figure 1 open circles) and therefore $K_{2}=8$ for the survey. The total number of stations occupied along each transect in the two surveys is summarized in Table 1.

Both surveys were conducted during July-August with the 18.6 m government research vessel, the M.V. MARINUS.

A11 tows were made with a gang of four toothless Digby buckets (effective mouth opening of 2.9 m ), mounted on a single tow bar. Dredges were equipped with $2 \frac{1}{2} / 1$ ( 6.4 cm ) rings and carried a $1^{\prime \prime}(2.5 \mathrm{~cm})$ nylon net liner on the inside of the bag to increase retention of smaller scallops. The liner was inspected frequently and repaired or replaced as necessary.

Dredges were hauled up at the end of each tow and the catch was "bushelled" into baskets and weighed to the nearest pound. Shell-height measurements (to the nearest mm ) were performed on either the whole catch, or a random subsample, depending on the amount caught and anticipated arrival time at the next station. When subsamples were employed, counts were made of all animals not measured.

Marked sounder records with start and finish positions were brought back to the lab to ensure that tows were in fact 0.25 nautical miles in length. When deviant, catches were adjusted accordingly based on the observation made during the preliminary trials that the amount caught was found proportional to distance towed.

## II. Estimation

The estimators of the mean and population total are straight forward, that is:

$$
\begin{align*}
& \bar{Y}_{\text {syst }}=\frac{1}{n_{1} n_{2}} \sum_{i=1}^{n_{1}} \sum_{j=1}^{n_{1}} \quad Y_{i j},  \tag{1}\\
& Y_{\text {syst }}=N \bar{Y}_{\text {syst }} . \tag{2}
\end{align*}
$$

The above formula for the mean is the general equation for the case of a rectangular lattice but is modified for our design since the transects are not of equal length to:

$$
\bar{Y}_{\text {syst }}=\left(\begin{array}{cc}
n_{1} &  \tag{3}\\
\sum_{i=1} & n_{2 i}
\end{array}\right)^{-1} \quad n_{1} \quad n_{2 i} \quad l
$$

The population total formula remains the same. As discussed in Smith and Naidu (1981) the sampling variance of $\bar{Y}_{\text {syst }}\left(V_{s y}\right)$ for a rectangular lattice is defined to be:

$$
\begin{equation*}
V_{s y}=\frac{1}{K_{1} K_{2}} \sum_{\Gamma=1}^{K_{1}} \sum_{s=1}^{K_{2}} \quad\left(\bar{Y}_{1, s}-\bar{Y}\right)^{2}, \tag{4}
\end{equation*}
$$

where $\bar{Y}_{1, s}$ denotes a particular mean obtained from one of the $K_{1} K_{2}$ possible samples and $\bar{Y}$ is the mean of the whole population. Since from any one systematic sample we will have only one value for $\bar{\gamma}_{7, s}$ the variance cannot be estimated by using equation 4 . Three approaches are available to circumvent this problem. The first assumes that the population units are in random order and therefore the estimator reduces to that used in random sampling. In sampling natural populations (see references in Cochran 1977 and Jumars et a1. 1977) it has been observed that samples taken close together in space are more likely to be similar in value than those taken farther apart due to there being spatial autocorrelation present or a trend or both. The second approach assumes some model to take these effects into account in order to devise an appropriate estimator of the variance (Cochran 1977, Heilbron 1978, Smith and Naidu 1981). The third approach uses a hybridization of a systematic scheme with some other method but has yet to be extended to the lattice situation (Stephan 1969, Singh and Singh 1977, Zinger 1980).

In this paper we will consider the first two approaches listed above.

## RESULTS

The numbers and weights of scallops caught in the 1980 and 1981 surveys are listed in Table 2. The relative positions of the 1980 samples and the associated observed values are presented in Table 3a and 4a.

Before the variance of the mean of these observations can be estimated the null hypothesis of randomness of the sample values must be tested. This is carried out by applying the spatial autocorrelation tests developed by Cliff and Ord (1973) (also see Jumars et al. 1977 for applications of these tests to benthic sampling data). These tests which were developed for demographical and earth sciences problems are weighted forms of Moran's "I" and Geary's "C" statistics both of which have seen use in the ecological literature for summarizing dispersion and diversity patterns. Since Cliff and Ord (1973) discuss the statistics and their properties we will not dwell on these aspects here. Instead we will present the forms of the statistics I and C used here and briefly review their interpretation.

Define,

$$
\begin{aligned}
& \mathrm{n}=\text { number of samples, } \\
& y_{i j}=\text { variate value of the } i j \text { th sample (in the grid), } \\
& Z_{i j}=Y_{i j}-\bar{y}, \\
& W=\begin{array}{lllll}
n & n & n & n \\
i & \sum & \sum & \sum \\
j & k & 1
\end{array}, W_{i j k l} . \quad \text { where } i \neq k \text { and } j \neq 1 \\
& I=\left(\frac{n}{W}\right) \begin{array}{llll}
n & n & n & n \\
\sum & \sum_{j} & \sum \cdot \sum \\
i & k & 1
\end{array} W_{i . j k l} \quad Z_{i j} Z_{k l} \text { where again } i \neq k, j \neq 1 \text {, } \\
& \sum_{i}^{n} \sum_{j}^{n} Z_{i j}{ }^{2}
\end{aligned}
$$

and,

$$
C=\left(\frac{n-1}{2 W}\right) \frac{n}{n} \begin{array}{llll}
n & n & n \\
i & j & k & 1
\end{array} \frac{W_{i j k l}\left(x_{i j}-x_{k l}\right)^{2}}{\sum \sum \sum Z_{i j}{ }^{2}} \quad(i \neq k, j \neq 1)
$$

The weighting factor $W_{i j k l}$ in the above formulae is defined in such a way as to provide all the spatial information assumed in the model being entertained under the alternative hypothesis. The null hypothesis for both of the test statistics above is that there is no spatial autocorrelation present i.e. the values are in random order. Under this null hypothesis the expected values of $I$ and $C$ are $-(n-1)^{-1}$ and 1 respectively. The significance of the differences from these expected values are
tested assuming a Gaussian distribution for I and C (Cliff and Ord 1973). Positive autocorrelation is determined when the observed value of the test statistic I is greater than the expected value and $C$ is smaller than the expected. Negative autocorrelation is indicated when the reverse is observed.

Since the validity of the test results depend upon the choice of the $W_{i j k l}$ values used we define our alternative hypothesis in an analagous manner to that used in Cliff and Ord (1973) for autoregressive models of the Gaussian-Markov type. That is since adjacent sample units were equidistant along one direction only, the tests of the relationships were subdivided into the orientations where equal distances between samples were obtained. These relationships were denoted by describing them as movements undertaken by chess pieces on a chess board in combination with compass directions, e.g. Rook (E-W) denotes relationships between samples along a transect and Rook ( $N-S$ ) relationships between samples across transects. Bishop moves were along the diagonally arranged samples. The weights were defined as follows:
$W_{i j k l}=1 / d$, where $d$ is the total number of joins between adjacent samples.

The tests were carried out separately for samples one and two sample units apart and extended to three if the results were significant at the second order difference. The results of the tests for 1980 for both numbers and weights are presented in Table 5. From these results we can see that there is evidence of positive autocorrelation along transects (Rook E-W) for both numbers and weights when samples are 1 and 2 nautical miles apart. Further there also seems to be a like relationship along the diagonal denoted by Bishop (SE-NW) when samples are $2 \sqrt{2}$ miles distant (order $=2$ ) and $3 \sqrt{2}$ miles distant (numbers only, order $=3$ ). The 1981 results are not presented due to the conclusions being the same with the exception that only the test for the first order distance ( $\sqrt{2}$ miles) was significant for the Bishop (SE-NW) test.

Although these tests indicate that there is enough evidence to reject the null hypothesis of random arrangement along transects and along one diagonal they do not by themselves prove that spatial autocorrelation is the only factor at work here. One of the assumptions required to use the variance estimator studied in Smith and Naidu (1981) which assumes spatial autocorrelation, is that there be stationarity present (interpreted to mean absence of trend here). In Table 3b we have depicted the positions of observations of numbers of scallops caught in the 1980 survey whose values are greater than the mean (1) and less than the mean ( -1 ). From this table we can see that there is a definite trend in the data such that sample values from the more southerly areas (top of table) tend to be greater than the mean and the northerly areas less than the mean in value. This pattern is again seen for the weights observed (Table 4b) and is also present in 1981 (Tables 6a and 6b) although less well defined probably due to there being fewer samples taken.

To deal with this trend we considered conceptualizing the data in the following manner (after Tukey 1977);

$$
\text { DATA }=\text { FIT + Residual }
$$

If we can determine the "Fit" or trend in the data and remove it successfully then the stationarity assumption may be met. The variance then would be obtained from the residuals. Since the trend appears to be non-linear in form it was decided not to employ linear regression techniques to find a fit instead we decided to use the smoothing techniques described in Tukey (1977). Since the autocorrelation tests indicated that between transects samples appeared to be uncorrelated the smoothing was carried out along transects. The diagonal results obtained from the autocorrelation tests were assumed to be confounded by the trend.

Smoothing the transect sequences was carried out as follows: 1) smooth points by replacing each point with the median of it and the two adjacent points, continuing this operation until no further changes occur in the sequence then, 2) smooth the sequence further by taking a running average 3 points at a time but giving the point which is being replaced a weight of 0.5 and the adjacent points a weight of 0.25 . This latter process is referred to as "Hanning" in Tukey (1977). When the smoothed sequences were plotted against the actual values for each transect (too many plots to reproduce here) it was found that a great deal of the trend was accounted for. The residual component was obtained by subtracting the "Fit" from the data and then we tested for the presence of the trend noted earlier by tabling the values according to their position and value in relation to their mean. These results are included as Tables 7 and 8. It appears from these tables that the original pattern is no longer present and therefore we will assume that any obvious trends no longer exist.

The next thing to determine is whether or not there is any spatial autocorrelation present in the detrended data. Again applying the tests using the I and C statistics we find that positive spatial autocorrelation only exists now for Rook's relationship ( $\mathrm{E}-\mathrm{W}$ ) order $=1$ for numbers caught in 1980. There is some consistency in this result when compared to the results in 1981 as the test for Rook (E-W) order $=2$ (1980) is testing the same distance measure as is in 1981 order $=1$ since the samples taken were spaced twice as far and both tests indicated the null hypothesis could not be rejected. Wi.th the exception of numbers in 1980 there is no evidence to reject the null hypothesis of randomness for the other variates that were measured and therefore it appears that the autocorrelation pattern noted in the original was mainly due to the trend observed. The variances of the means for these results can be estimated under the assumption of randomness by the following formula:

$$
v_{s y}=\operatorname{Var}(\bar{y})=\left(\frac{N-n}{N n}\right) s^{2}
$$

where $S^{2}$ is the sample variance of the residuals.

For the numbers caught in 1980 we will use a modified form of the sample-based approximation to the unconditional expected value of the true variance studied in Smith and Naidu (1981). To use this we will assume that a Markov stationary model describes the autocorrelation pattern seen in the residuals. The estimate of the variance is obtained by the following formula:

$$
V_{s y}=\left(\frac{N-1}{N}\right) s^{2} \quad\left\{1-\frac{1}{N(N-1)} \quad \sum_{\nu} A_{\hat{\rho} 0, v}-\frac{n-1}{n}+\frac{1}{n^{2}} \sum B \hat{\rho}_{0, k_{2} v}\right\}
$$

where $N, n$, and $S^{2}$ are as previously defined. The values $\hat{\rho}_{0, v}$ and $\hat{\rho}_{0, k_{2} v}$ represent the estimated autocorrelations between samples along transects between population units "v" units apart and population units $K_{2} v$ units apart (i.e. sample units) respectively, as per Smith and Naidu (1981). As we are assuming a Markov - stationary model we define $\rho_{0, v}=\rho^{v}$ and $\hat{\rho}_{0, k_{2} v}=\hat{\rho}^{k} 2^{v}$. Since the presence of positive autocorrelation was found to be significant at order $=1$ for numbers caught we use this estimate $\left(\hat{\rho}^{K}{ }^{2} V=\hat{\rho}^{4}=0.8425\right)$ to find our estimates for $\hat{\rho}^{V}$. It should be noted that the estimated autocorrelation for order $=2$ was $\rho^{8}=0.6572$ which although not significant when tested is still close to, what would be expected under this kind of model $\left(\left(\rho^{4}\right)^{2}=0.7098\right)$. We define $B$ in the above equation to be the number of samples which contribute to this autocorrelation (i.e. $2 \times\left(n-11 v\right.$ ) assuming $\rho_{0, k_{2} v}=\rho_{0,-k_{2} v}$ ) and $A$ is an analogous quantity for the population units i.e. $B=2\left(N-K_{2} n_{1} v\right)$.

The results of these calculations for the variances and the means for numbers and weights for 1980 and 1981 are presented in Table 9.

## DISCUSSION

This is certainly not the first application of a systematic type of sampling scheme to marine data but it is the first time that we know of where the use of spatial information has been made when sampling this type of material. We know of three studies previous to our own where systematic sampling has been studied in order to determine if the scheme will provide more precise estimates of the population mean than random or stratified type of designs. Two of these studies, namely Venrick (1978) and Lenarz and Adams (1980) use empirical results to compare the precision obtained from each type of scheme. In both studies the precision of the mean was estimated assuming random order although in the first case there was a definite trend in the data and in the second the sample was assumed to be the population and a quasi-subsampling approach was carried out.

Estimation of the variance by a subsampling approach was investigated in Smith and Naidu (1981) and was found to be a very inefficient estimator.

The approach taken here to deal with the trend noted in the data may not be accepted by some due to the lack of rigour of the smoothing techniques. Explanatory variables such as depth and/or position were considered as possibilities for a least squares type of trend surface curve, but the apparent lack of a relationship exhibited when the variate values were plotted against depth and the arbitrariness of using the positions deterred us from continuing in this direction for the moment. Although we would agree that this line should be pursued farther it is still important to emphasize how powerful the smoothing techniques were in picking out the trends along the transects. The trends extracted from each transect did not parallel each other but instead showed definite individual patterns.

From the results of the survey in Table 9 we note that $95 \%$ confidence intervals (calculated assuming a Gaussion distribution for $\bar{\gamma}_{s t}$ ) for the estimated mean numbers of scallops do not quite overlap although the confidence intervals for the estimated mean weight per tow do. We can assume therefore given the distributional assumption the survey results indicate that the population size (numbers or weights) has changed very little between the two years.

In order to express these results in terms of estimated exploitable biomass we must take the efficiency of the sampling gear into account. It has been shown that the efficiency of scallop dredges varies with the type of bottom over which fishing takes place. Dickie (1955) found that the efficiency (or captures of sea scallops Placopecten magellanicus by means of recapturing tagged individuals, with commercial gear (25/8" rings) varied on the order of $5 \%$ for rough inshore areas to $12 \%$ for the smoother offshore areas. Overall efficiency for this study is assumed to be $15 \%$ and therefore total biomass is estimated to be $16,433 \mathrm{mt}$ and $20,000 \mathrm{mt}$ for 1980 and 1981 respectively. Comparison of these estimated total weights to the landings reported by the commercial fishery for 1980 and 1981 ( 1092 and 1488 mt respectively) indicate that the amount removed was on the order of $6.65 \%$ and $7.44 \%$ respectively for the two years.

The gear efficiency assumed here is probably a conservative estimate and for the present we feel that the biomass estimates herein derived are to be used as relative indices of abundance rather than absolute estimates.

As a final note we would like to draw the readers attention to the fact that coefficients of variation (i.e. $S E / \bar{Y}_{s t}$ ) range from $7.6 \%$ to $5.4 \%$ for our data.

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Table 1. Number of stations occupied along each transect during the two survey years.

| Transect No. | No of stations occupied <br> 1980 | Totals |  |
| :---: | :---: | :---: | :---: |
| 1 | 7 | 5 | 12 |
| 2 | 0 | 5 | 5 |
| 3 | 8 | 5 | 13 |
| 4 | 8 | 4 | 12 |
| 5 | 10 | 5 | 15 |
| 6 | 12 | 6 | 18 |
| 7 | 13 | 7 | 20 |
| 8 | 13 | 6 | 19 |
| 9 | 13 | 7 | 20 |
| 10 | 12 | 6 | 18 |
| 11 | 7 | 3 | 10 |
|  | 103 | 59 | 163 |
| Totals |  |  |  |

Table 2. Numbers and (weights[ of scallops caught per tow in 1980 and 1981.

| Transect No. | Station No. | 1980 | 1981 |
| :---: | :---: | :---: | :---: |
| 1 | 208 | 106(9.1) |  |
|  | 209 |  | 154(12.1) |
|  | 210 | 115(9.1) |  |
|  | 212 | 147(11.3) |  |
|  | 213 |  | 242(19.9) |
|  | 214 | 95(8.2) |  |
|  | 216 | 154(11.3) |  |
|  | 217 |  | 211(16.3) |
|  | 218 | 206(16.3) |  |
|  | 220 | 222(17.2) |  |
|  | 221 |  | 367(25.9) |
| 2 | 225 |  | 110(7.3) |
| 2 | -229 |  | 444(32.3) |
|  | 233 |  | 319 (24.5) |
|  | 237 |  | 325(25.0) |
|  | 241 |  | 248(19.9) |
|  | 245 |  | $67(6.3)$ |
| 3 | 001 |  | 107(8.3) |
|  | 002 | 187(13.6) |  |
|  | 004 | 246(18.2) |  |
|  | 005 |  | 22(1.3) |
|  | 006 | 279(20.0) |  |
|  | 008 | 233(20.4) |  |
|  | 009 |  | 83(5.7) |
|  | 010 | 414(36.7) |  |
|  | 012 | 151(13.6) |  |
|  | 013 |  | 179(14.3) |
|  | 014 | 38(2.7) |  |
|  | 016 | 282(20.9) |  |
|  | 017 |  | 200(13.2) |
| 4 | 28 | 104(8.2) |  |
|  | 29 |  | 71(5.8) |
|  | 30 | 77(5.9) |  |
|  | 32 | 105(8.6) |  |
|  | 33 |  | 39(2.7) |
|  | 34 | 44(2.7) |  |
|  | 36 | 50(4.5) |  |
|  | 37 |  | 227(21.4) |
|  | 38 | 28(2.3) |  |
|  | 40 | 20(0.9) |  |
|  | 41 |  | 5(0.5) |
|  | 42 | 212(19.5) |  |
|  | 44 | $7(0.5)$ |  |
|  | 45 |  | 118(10.6) |
|  | 46 | 16(0.9) |  |
|  | 48 | 110(9.5) |  |

Table 2. continued

| Transect No. | Station No. | 1980 | 1981 |
| :---: | :---: | :---: | :---: |
| 5 | 49 |  | 258(21.4) |
|  | 50 | 79(7.7) |  |
|  | 52 | 152(15.0) |  |
|  | 53 |  | 109(7.2) |
|  | 54 | 204(15.4) |  |
|  | 56 | 182(18.1) |  |
|  | 57 |  | 139(10.1) |
|  | 58 | 111(6.4) |  |
|  | 60 | 157(10.9) |  |
|  | 61 |  | 242(15.7) |
|  | 62 | 259(21.3) |  |
| 6 | 64 | 62(5.0) |  |
|  | 65 |  | 207(14.3) |
|  | 66 | 218(18.1) |  |
|  | 68 | 83(5.4) |  |
|  | 69 |  | 320 (28.0) |
|  | 70 | 180(14.1) |  |
|  | 72 | 99(5.9) | 103(8.4) |
|  | 74 | 106(7.3) | 103(8.4) |
|  | 76 | 142(10.9) |  |
|  | 77 |  | 49(3.8) |
|  | 78 | 4(0.5) |  |
|  | 80 | 56(5.0) |  |
|  | 81 |  | 128(10.7) |
|  | 82 | $2(0.5)$ |  |
|  | 84 85 | $7(0.5)$ | 148(13.4) |
|  | 86 | 9(0.7) | 148(13.4) |
| 7 | 88 | $33(2.3)$ |  |
|  | 89 |  | 39(3.6) |
|  | 90 | 195(15.9) |  |
|  | 92 | 30 (2.3) |  |
|  | 93 |  | 74(6.1) |
|  | 94 | 102(7.3) |  |
|  | 96 | 24(1.8) |  |
|  | 97 |  | 39(3.9) |
|  | $\begin{array}{r}98 \\ 100 \\ \hline\end{array}$ | $78(5.9)$ |  |
|  | 100 | 83(7.7) |  |
|  | 102 |  | 11 (1.0) |
|  | 104 | $36(1.8)$ |  |
|  | 105 |  | 71(7.1) |
|  | 106 | 23(1.4) |  |
|  | 108 | 41(2.7) |  |
|  | 109 |  | 108(9.7) |

Table 2. continued

| Transect No. | Station No. | 1980 | 1981 |
| :---: | :---: | :---: | :---: |
|  | 110 | 16(1.4) |  |
|  | 112 | 52(4.5) |  |
|  | 113 |  | 48(4.3) |
| 8 | 114 | 75(5.9) |  |
|  | 116 | 25(2.3) |  |
|  | 117 |  | 46(4.3) |
|  | 118 | 15(0.9) |  |
|  | 120 | 128(9.5) |  |
|  | 121 |  | 8(0.9) |
|  | 122 | 78(7.7) | (0.9) |
|  | 124 | 23(1.4) |  |
|  | 125 |  | 69(7.8) |
|  | 126 | 68(6.4) | 69(7.8) |
|  | 128 | 38(3.2) |  |
|  | 130 | 79(7.3) | 53(5.8) |
|  | 132 | 81(8.6) |  |
|  | 133 |  | 91(9.8) |
|  | 134 | 124(11.3) |  |
|  | 136 | 272(23.6) |  |
|  | 137 |  | 65(6.6) |
| 9 | 138 | 278(22.7) | 65(6.6) |
|  | 140 | 47(5.4) |  |
|  | 141 |  | 113(7.7) |
|  | 142 | 22(2.7) |  |
|  | 144 | 151(14.5) |  |
|  | 146 | 98(10.4) | 185(15.2) |
|  | 148 | 65(6.4) |  |
|  | 149 |  | 96(9.5) |
|  | 150 | 46(5.4) |  |
|  | 152 | 28(3.2) |  |
|  | 153 |  | 112(8.5) |
|  | 154 | 74(6.8) |  |
|  | 157 | 124(10.9) | 76(5.3) |
|  | 158 | 103(9.5) |  |
|  | 160 | 25(2.3) |  |
|  | 161 |  | 82(6.4) |
|  | 162 | 47(5.0) |  |
|  | 164 | 29(2.7) |  |
|  | 165 |  | 57(4.5) |
| 10 | 168 | 120(13.6) |  |
|  | 169 170 | 53(6.8) | 86(7.1) |
|  | 172 | 114(15.0) |  |

Table 2. continued

| Transect No. | Station No. | 1980 | 1981 |
| :---: | :---: | :---: | :---: |
|  | 173 |  | 81 (6.8) |
|  | 174 | 97(11.8) |  |
|  | 176 | 92(11.3) |  |
|  | 177 |  | 113(10.2) |
|  | 178 | 52(7.7) |  |
|  | 180 | 13(1.8) |  |
|  | 181 |  | 128(12.6) |
|  | 182 | 55(6.4) |  |
|  | 184 | 122(13.2) |  |
|  | 185 |  | 94(9.1) |
|  | 186 | 107(11.3) |  |
|  | 188 | 86(8.2) |  |
|  | 189 |  | 110(10.6) |
|  | 190 | 59(5.9) |  |
|  | 192 | 68(7.3) |  |
|  | 193 |  | 108(11.6) |
|  | 194 | 102(10.9) |  |
|  | 196 | 122(12.3) |  |
|  | 197 |  | 19(3.0) |
|  | 198 | 42(5.0) |  |
|  | 200 | 34(4.5) |  |
|  | 201 |  | 27(3.5) |
|  | 202 | $11(1.8)$ $43(4.5)$ |  |
|  | 204 | 43(4.5) |  |

Table 3.(a) Schematic representation of numbers of scallops caught 1980

Transect


Table 3(b) Position of observations greater than (1) or less than (-1) the mean in value. Mean 97.981

Transect


Table 4. (a) Schematic representation of weights of scallops caught - 1980 (x10).

Transect

| 1 |  |  |  |  |  |  |  |  | 91 |  | 97 |  | 113 |  | 82 |  |  | 113 |  | 163 |  | 17 |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 2 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 3 |  |  |  |  |  |  | 136 |  | 182 |  | 20 |  | 204 |  | 367 |  |  | 136 |  | 27 |  | 20 |  |  |  |  |  |  |
| 4 |  |  |  |  |  | 195 |  | 09 |  | 23 |  | 45 |  | 27 |  |  | 86 |  | 59 |  | 82 |  |  |  |  |  |  |  |
| 5 |  |  |  |  |  |  | 05 |  | 09 |  | 95 |  | 77 |  | 15 |  |  | 154 |  | 181 |  | 6 |  |  | 09 |  | 213 |  |
| 6 |  |  |  | 07 |  | 05 |  | 05 |  | 5 |  | 05 |  | 109 |  |  | 73 |  | 59 |  | 141 |  |  |  |  | 81 |  | 5 |
| 7 | 23 |  | 159 |  | 23 |  | 73 |  | 18 |  | 59 |  | 77 |  | 68 |  |  | 18 |  | 14 |  | 2 |  |  | 14 |  | 45 |  |
| 8 |  | 227 |  | 236 |  | 163 |  | 86 |  | 73 |  | 32 |  | 64 |  |  | 14 |  | 77 |  | 95 |  | 0 | 9 |  | 23 |  | 59 |
| 9 | 54 |  | 27 |  | 145 |  | 104 |  | 64 |  | 54 |  | 32 |  | 68 |  |  | 109 |  | 95 |  | 2 |  |  | 05 |  | 27 |  |
| 10 |  | 59 |  | 82 | - | 113 |  | 132 |  | 64 |  | 18 | 8 | 77 |  |  | 13 |  | 118 |  | 15 | 5 |  | 8 |  | 36 |  |  |
| 11 | 73 |  | 109 | . | 123 |  | 5 |  | 45 |  | 18 |  | 45 | 5 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

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Table 4. (b) Position of observations greater than (1) or less than ( -1 ) the mean in value. Mean $=8.479$
Transect


Table 5. Results of autocorrelation tests for numbers and weights of scallops caught in 1980 survey.


Table 6. (a). Position of observations (numbers) greater than (1) or less than the mean in value from 1981 survey (mean $=126,271$ )

Transect


Table 6.(b) Position of observations (weights) greater than (1) or less than the mean in value from 1981 survey (mean $=10.319$ ).
$\qquad$
Transect


Table 7. (a). Position of residuals (numbers) greater than (1) or less than ( -1 ) the mean in value 1980.

Transect


Table 7. (b) Position of residuals (weights) greater than (1) or less than ( -1 ) the mean in value 1980

Transect


Table 8. (a). Position of residuals (numbers) greater than (1) or less than ( -1 ) the mean in value (1981).

Transect


Table 8. (b) Position of residuals (weights) greater than (1) or less than (-1) the mean in value 1981.

Transect


Table 9. Results of Iceland scallop surveys in the northeastern Gulf of St. Lawrence in 1980 and 1981.

| 1980 | 1981 |
| :--- | :--- | :--- |

A. Numbers
$\overline{Y_{s}}$ t
Vsy
S.E. ( $\overline{Y_{S}} t$ )

95\% C.I. for mean
MIB (nos)
B. Weights

At $15 \%$ gear efficiency (MT)
At 20\% gear efficiency (MT)

| $\bar{Y}_{s t}$ | 8.48 | 10.32 |
| :---: | :---: | :---: |
| Vsy | 0.195 | 0.328 |
| S.E. ( $\bar{Y}$ st) | 0.441 | 0.572 |
| 95\% C.I. for mean | 7.60-9.36 | 9.20-11.43 |
| MIB (MT) | 2,465 | 3,000 |

16,436
20,002
97.9
126.3
55.8
46.3
$7.47 \quad 6.80$
83.0-112.9 112.6-139.8
28.5 m
36.7 m
.20-11. 43
3,000


Fig. 1. Distribution of fishing stations

